

Key features

- Configurable receiver, scalable for future requirements.
- Available in base & rover, rover only, or base only configurations.
- Trimble[®] Inertial Platform[™] technology for magnetically immune IMU-based tilt compensation.
- Trimble ProPoint[™] GNSS positioning engine for improved accuracy and productivity in challenging GNSS conditions.
- Trimble Maxwell[™] 7 GNSS ASIC.
- 9 GB internal memory.
- Trimble xFill[®] correction outage technology.

- Supports Trimble CenterPoint[®] RTX corrections for RTK level accuracy worldwide via satellite/IP.
- Military-grade ultra-rugged design, IP68 rating.
- Optimized for Trimble Access[™] field software.

Find out more at: geospatial.trimble.com/R780



Trimble R780

GNSS System

DATASHEET



	TIONS	
PERFORMANCE SPECIFICA		
GNSS TECHNOLOGY		
	integration with Trimble ProPoint GNSS technology	positioning in challenging environments ¹ and inertial measurement
		raceability with Trimble TIP™ technology IMU-based tilt compensation
	Trimble RTX worldwide corrections	
	Advanced Trimble Maxwell 7 technology	
	Trimble EVEREST Plus [™] multipath signal rejection	
	Spectrum Analyzer to troubleshoot GNSS jamming	
	Anti-spoofing capabilities	
	Japanese LTE Filtering below 1510 MHz allows antennas	to be used 100 m away from Japanese LTE cell tower
	Iridium Filtering above 1616 MHz allows the antenna to be	
SATELLITE TRACKING		s used zo maway nominalam transier
	GPS: L1C, L1 C/A, L2E (L2P), L2C, L5	
	GLONASS: L1C/A, L1P. L2C/A, L2P, L3	
	Galileo: E1, E5A, E5B and E5AltBOC, E6 ²	
	BeiDou: B1, B2, B3, B1C, B2A	
	QZSS: L1 C/A, L1C, L1S, L2C, L5, LEX/L6	
	SBAS: L1 C/A (EGNOS/MSAS GAGAN/SDCM), L1 C/A ar	ICLS(WAAS)
	L-Band: Trimble RTX	
POSITIONING PERFORMAN		
STATIC GNSS SURVEYING		
High-Precision Static		
<u> </u>	Horizontal	3 mm + 0.1 ppm RMS
	Vertical	3.5 mm + 0.4 ppm RMS
Static and Fast Static	Voltiour	
	Horizontal	3 mm + 0.5 ppm RMS
	Vertical	5 mm + 0.5 ppm RMS
REAL TIME KINEMATIC SURVE		5 mm + 0.5 ppm RMS
	TING	
Single Baseline < 30 km		0
	Horizontal	8 mm + 1 ppm RMS
	Vertical	15 mm + 1 ppm RMS
Network RTK ⁴		
	Horizontal	8 mm + 0.5 ppm RMS
	Vertical	15 mm + 0.5 ppm RMS
	RTK start-up time for specified precisions ⁵	2 to 8 seconds
TRIMBLE INERTIAL PLATFORM	1 (TIP) TECHNOLOGY	
TIP Compensated Surveying ⁶		
	Horizontal	RTK + 8 mm + 0.5 mm/° tilt (up to 30°) RMS
	Horizontal	RTX + 8 mm + 0.5 mm/° tilt (up to 30°) RMS
IMU Integrity Monitor	Bias monitoring	Temperature, age and shock
TRIMBLE RTX CORRECTION SE	ERVICES	
CenterPoint RTX ⁷		
	Horizontal	2 cm RMS
	Vertical	5 cm RMS
	RTX convergence time for specified precisions in	
	Trimble RTX Fast regions	<1 min
	RTX convergence time for specified precisions in non	< 3 min
	RTX Fast regions RTX QuickStart convergence time for specified precisions	< 5 min
TRIMBLE xFILL ⁸	Any Querotari convergence time for specified precisions	No min
	Horizontal	RTK ⁹ + 10 mm/minute RMS
	Vertical	RTK ⁹ + 20 mm/minute RMS
TRIMBLE xFILL PREMIUM ⁸	Llevizentel	2 om DMC
	Horizontal	3 cm RMS
	Vertical	7 cm RMS

DATASHEET

Trimble R780

GNSS System



POSITIONING PERFORMANC	E ³ Cont.	
CODE DIFFERENTIAL GNSS POS		
	Horizontal	0.25 m + 1 ppm RMS
	Vertical	0.50 m + 1 ppm RMS
	SBAS ¹⁰	Typically < 5 m 3DRMS
HARDWARE		
PHYSICAL		
Dimensions (W×H)	13.9 cm x 13 cm (5.5 in x 5.1 in) inc	luding connectors
Weight	1.55 kg (3.42 lb) receiver only including radio and battery	
Temperature ¹¹		5 , , , , , , , , , , , , , , , , , , ,
·	Operating	-40 °C to +65 °C (-40 °F to +149 °F)
	Storage	-40 °C to +75 °C (-40 °F to +167 °F)
Humidity	0	100%, condensing
Ingress protection		IP68 Certified per IEC-60529: waterproof/dustproof (1 m submersion for 1 hour)
Shock and vibration		······································
	Pole drop	Designed to survive a 2 m (6.6 ft) pole drop onto concrete
	Shock	Non-operating: 75 Gs at 6msec
	Shock	Operating: 40 Gs at 10msec
	Vibration	Mil-Std-810G, FIG 514.6E-1 Cat 24, Mil-Std-202G, FIG 214-1, Condition D
ELECTRICAL	- Instation	
	Internal	Rechargeable, removable Lithium-ion battery in internal battery compartment
		Internal battery operates as a UPS during an ext power source failure
		Internal battery will charge from external power source as long as source can support the power drain and is more than 11.8 VDC
		Integrated charging circuitry
	External	External power input with over-voltage protection on Port 1 (7-pin Lemo 2-key) Minimum 10.8 V, Maximum 28 VDC, shutdown optimized for 12 V lead acid battery operation
		Power source supply (Internal/External) is hot-swap capable in the event of power source removal or cut off DC external power input with over-voltage protection on
		Port 1 (Lemo)
	Devene	Receiver automatically turns on when connected to external power
	Power consumption	3.2 W in rover mode with internal receive radio ¹²
		5.2 W in base mode with internal 0.5 W transmit radio
Operating times on internal battery ¹³	Davian	
	Rover	5.5 hours; varies with temperature
	Base station 450 MHz systems	5.5 hours; varies with temperature
		Approximately 4 hours; varies with temperature
COMMUNICATIONS AND DAT	900 MHz systems	Approximately 4 hours; varies with temperature
Lemo (Serial 1)	7-pin Lemo 2-key, Power Input, USB. Optional USB to RS232 serial cable. Receiver supports RNDIS communications over USB	
Wi-Fi	Client or Access Point. Receive or transmit corrections. Wi-Fi b/g/n	
Bluetooth® wireless technology	Fully-integrated sealed 2.4 GHz Bluetooth module	
Integrated radios (optional)	Fully-integrated sealed 2.4 GHz bidetooth module Fully-integrated, fully-sealed internal 403-473 MHz; Internal 900 MHz; Rx/Tx	
Channel spacing (450 MHz)	12.5 kHz or 25 kHz spacing available	
Sensitivity (450 MHz)	-114 dBm (12 dB SINAD)	
450 MHz output power	0.5 W, 2.0 W, depending on the local required licensing.	
Frequency approvals (403–473 MHz)	Worldwide, depending on the local required licensing.	
Positioning rates	1 Hz, 2 Hz, 5 Hz, 10 Hz, and 20 Hz	
Data storage	9 GB internal data logging. Moving base and heading	
-	CMR+, CMRx, RTCM 2.1, RTCM 2.3, RTCM 3.0, RTCM 3.1, RTCM 3.2 input and output	
Data format	24 NMEA outputs, GSOF, RT17, and	

DATASHEET

Trimble R780

GNSS System



CERTIFICATIONS		
	FCC Part 15 Subpart B (Class B Device), Part 15.247, Part 90	
	Canadian ICES-003 (Class B), RSS-GEN, RS-102, RSS-247	
	IEC62368-1 2nd Edition	
	CISPR 32, EN 55032, EN 55035	
	RCM mark, AS/CISPR 32, AS/NZS 4768	
	Japan MIC	
	CE mark, Radio Equipment Directive (RED 2014/53/EU)	
	RoHS compliance	
	WEEE compliance	
TRIMBLE PROTECTED PROTECTION PLANS		

Add a Trimble Protected protection plan for worry-free ownership over and above the standard Trimble product warranty. Added enhancements include coverage for wear & tear, environmental damage, and more. Accidental damage is covered with Premium plans, available only at point-of-sale in selected regions. For details, visit trimbleprotected.com or contact a local Trimble distributor.

- 1 Challenging GNSS environments are locations where the receiver has sufficient satellite availability to achieve
- 2
- Challenging GNSS environments are locations where the receiver has sufficient satellite availability to achieve minimum accuracy requirements, but where the signal may be partly obstructed by and/or reflected off of trees, buildings, and other objects. Actual results may vary based on user's geographic location and atmospheric activity, scintillation levels, GNSS constellation health and availability, and level of multipath and signal occlusion. The current capability in the receivers is based on publicly available information. As such, Trimble cannot guarantee that these receivers will be fully compatible with a future generation of Gallieo satellites or signals. Precision and reliability may be subject to anomalies due to multipath, obstructions, satellite geometry, and atmospheric conditions. The specifications stated recommend the use of stable mounts in an open sky view, EMI and multipath clean environment, optimal GNSS constellation configurations, along with the use of survey practices that are generally accepted for performing the highest-order surveys for the applicable application including occupation times appropriate for baseline length. Baselines longer than 30 km require precise ephemeris and occupations up to 24 hours may be required to achieve the high precision static specification. Network RTK PPM values are referenced to the closest physical base station. May be affected by atmospheric conditions, signal multipath, obstructions and satellite geometry. Initialization reliability is continuously monitored to ensure highest quality. TIP references the overall positioning error estimate at the tip of the surveying pole throughout the tilt compensation range. RTK refers to time stimate horizontal precision of the underlying GNSS position, which is dependent on range. RTK heres to time stimate horizontal precision of the underlying GNSS position, which is dependent on
- 5
- 6
- range, RTK refers to the estimated horizontal precision of the underlying GNSS position, which is dependent on factors that affect GNSS solution quality. The 8 mm constant error component accounts for residual misalignment between the vertical axes of the receiver and the built-in Inertial Measurement Unit (IMU) after factory calibration, assuming the receiver is mounted on a standard 2 m carbon fiber range pole which is properly calibrated and free from physical defects. The tilt-dependent error component is a function of the quality of the computed tilt azimuth, which is assumed here to be aligned using optimal GNSS conditions. For best IMU tilt compensated results, perform a pole bias adjustment.
- RMS performance based on repeatable in field measurements. Achievable accuracy and initialization time may avery based on type and capability of receiver and antenna, user's geographic location and atmospheric activity, scintillation levels, GNSS constellation health and availability and level of multipath including obstructions such as large trees and buildings.
- Accuracies are dependent on GNSS satellite availability. xFill positioning without an xFill Premium subscription ends after 5 minutes of radio downtime. xFill Premium will continue beyond 5 minutes providing the solution has converged, with typical precisions not exceeding 3 cm horizontal, 7 cm vertical. xFill is not available in all regions, check with your local sales representative for more information.

- cneck with your local sales representative for more information. 9 RTK refers to the last reported precision before the correction source was lost and xFill started. 10 Depends on SBAS system performance. 11 Receiver will operate normally to -40 °C, internal batteries are rated from -20 °C to +60 °C (ambient +50 °C). 12 Tracking GPS, GLONASS and SBAS satellites. 13 Varies with temperature and wireless data rate. When using a receiver and internal radio in the transmit mode, it is recommended that an external 6 Ah or higher battery is used.

Specifications subject to change without notice





NORTH AMERICA Trimble Inc. 10368 Westmoor Dr

USA

Westminster CO 80021 GERMANY

FUROPE Trimble Germany GmbH Am Prime Parc 11 65479 Raunheim

ASIA-PACIFIC

Trimble Navigation Singapore PTE Limited 3 HarbourFront Place #13-02 HarbourFront Tower Two Singapore 099254 SINGAPORE



© 2022–2023, Trimble Inc. All rights reserved. Trimble, the Globe & Triangle logo, xFill and CenterPoint are trademarks of Trimble Inc., registered in the United States and in other countries. Trimble Access, EVEREST, Maxwell, ProPoint and Trimble Inertial Platform are trademarks of Trimble Inc. iPad and iPhone are trademarks of Apple Inc., registered in the U.S. and other countries. The Bluetooth word mark and logos are owned by the Bluetooth SIG, Inc. and any use of trademarks of Apple Inc., registered in the U.S. and other countries. The Bluetooth word mark and logos are owned by the Bluetooth SIG, Inc. and any use of the second such marks by Trimble Inc. is under license. Galileo is developed under a License of the European Union and the European Space Agency, Google Play and the Google Play logo are trademarks of Google LLC. All other trademarks are the property of their respective owners. PN 022516-642B (04/23)